

Generating Loop Invariants for Program Verification by Transformation

G.W. Hamilton

School of Computing Dublin City University Dublin 9, Ireland hamilton@computing.dcu.ie

VPT 2017

	Language	Loop Invariants	Distillation	Our Approach	Conclusions
Outline					

- 1 Introduction
- 2 Language
- 3 Loop Invariants
- 4 Distillation
- 5 Our Approach
- 6 Examples





- The verification of imperative programs generally involves annotating the program with assertions.
 - A theorem prover can be used to check these.
- Central to this annotation process is the use of loop invariants.
 - These are assertions that are true before and after each iteration of a loop.
- Finding these invariants is a difficult and time-consuming task.
 - Programmers are therefore reluctant to do this.
- We present a technique for automatically discovering loop invariants using program transformation.
 - Avoids the possible exponential blow-up in the size of the assertions produced by other techniques.

Language

Syntax

```
S = SKIP
     V := E
      S_1 : S_2
     IF B THEN S_1 ELSE S_2
      BEGIN VAR V_1 \ldots V_n S END
     WHILE B DO S
F ::= V
     C E_1 \ldots E_k
     \lambda V.E
     F
```

 $E_0 E_1$

Do nothing Assignment Sequence Conditional Local block While loop

Variable Constructor Application λ -Abstraction **Function Call** Application case E_0 of $P_1 \rightarrow E_1 | \cdots | P_k \rightarrow E_k$ Case Expression E_0 where $F_1 = E_1 \dots F_n = E_n$ Local Function Definitions

< ロ > < 同 > < 三 > < 三 >



E corresponds to natural number expressions which belong to the following datatype:

```
Nat ::= Zero | Succ Nat
```

 ${\it B}$ corresponds to boolean expressions which belong to the following datatype:

Bool ::= True | False

We assume a number of pre-defined operators written in this language; these definitions are unfolded and folded during transformation:

- Arithmetic operators: +, -, *, /, %, ^
- Boolean operators: $\land, \lor, \neg, \Rightarrow$
- Relational operators: $<,>,\leq,\geq,=,\neq$

Partial Correctness

Floyd-Hoare Logic								
{ <i>P</i> } SKIP { <i>P</i> }	$\{Q\{V := E\}\}\ V := E\ \{Q\}$							
$\frac{\{P\} \ S_1 \ \{Q\}, \qquad \{Q\} \ S_2 \ \{R\}}{\{P\} \ S_1; S_2 \ \{R\}}$	$\frac{\{P \land B\} S_1 \{Q\}, \qquad \{P \land \neg B\} S_2 \{Q\}}{\{P\} \text{ IF } B \text{ THEN } S_1 \text{ ELSE } S_2 \{Q\}}$							
$\frac{\{P\} S \{Q\}, \qquad V_1 \dots V_n \notin fv(P), fv(Q)}{\{P\} \text{ BEGIN VAR } V_1 \dots V_n S \text{ END } \{Q\}}$								
$\frac{P \Rightarrow P', \qquad \{P'\} \ S \ \{Q\}}{\{P\} \ S \ \{Q\}}$	$\frac{\{P\} \ S \ \{Q'\}, \qquad Q' \Rightarrow Q}{\{P\} \ S \ \{Q\}}$							

< ロ > < 回 > < 回 > < 回 > < 回 >

æ



- A loop invariant is an assertion that is true before and after each iteration of the loop.
- Usually needs to be provided by the programmer.
- A program which is annotated in this way will have the form: {P} WHILE B DO {I} S {Q}
- The three requirements of the invariant *I* are as follows:
 - $P \Rightarrow I$ $\{I \land B\} S \{I\}$ $(I \land \neg B) \Rightarrow Q$

	Language	Loop Invariants	Distillation	Our Approach	Conclusions
Exampl	е				

$$\{n \ge 0\} \\ x := 0; \\ y := 1; \\ WHILE x < n DO \\ BEGIN \\ x := x + 1; \\ y := y * k \\ END \\ \{y = k^n\}$$

▲口 ▶ ▲母 ▶ ▲目 ▶ ▲目 ▶ ▲日 ● ● ● ●



 $\begin{cases} n \ge 0 \\ x := 0; \\ y := 1; \\ WHILE x < n DO \\ BEGIN \\ x := x + 1; \\ y := y * k \\ END \\ \{y = k^n\} \end{cases}$

 Invariant is often a weakening of the postcondition.

→ < Ξ → <</p>



$$\begin{cases} n \ge 0 \\ x := 0; \\ y := 1; \\ WHILE x < n DO \\ BEGIN \\ x := x + 1; \\ y := y * k \\ END \\ \{y = k^n\} \end{cases}$$

• Invariant is often a weakening of the postcondition.

• For example:
$$y = k^{\wedge}x$$

æ

-≣->

▲□ ► < □ ► </p>



$$\begin{cases} n \geq 0 \\ x := 0; \\ y := 1; \\ WHILE x < n DO \\ BEGIN \\ x := x + 1; \\ y := y * k \\ END \\ \{y = k^n\} \end{cases}$$

- Invariant is often a weakening of the postcondition.
- For example: $y = k^{\wedge}x$
- This does not satisfy the third requirement for an invariant:

 $\begin{aligned} y &= k^{\wedge} x \wedge \neg (x < n) \Rightarrow \\ y &= k^{\wedge} n \end{aligned}$



$$\begin{cases} n \geq 0 \\ x := 0; \\ y := 1; \\ WHILE \ x < n \ DO \\ BEGIN \\ x := x + 1; \\ y := y * k \\ END \\ \{y = k^n n \} \end{cases}$$

- Invariant is often a weakening of the postcondition.
- For example: $y = k^{\wedge}x$
- This does not satisfy the third requirement for an invariant:

 $\begin{aligned} y &= k^{\wedge} x \wedge \neg (x < n) \Rightarrow \\ y &= k^{\wedge} n \end{aligned}$

 The additional invariant x ≤ n is also required.



- We make use of the weakest liberal precondition originally proposed by Dijkstra.
 - This is denoted as *WLP*(*S*, *Q*), where *S* is a program and *Q* is a postcondition.
 - The condition P = WLP(S, Q) if Q is true after execution of S, and no condition weaker than P satisfies this.
 - The rules for calculating *WLP*(*S*, *Q*) for our programming language are as follows:

```
\begin{split} & WLP(\mathsf{SKIP}, Q) = Q \\ & WLP(V := E, Q) = Q\{V := E\} \\ & WLP(S_1; S_2, Q) = WLP(S_1, WLP(S_2, Q)) \\ & WLP(\mathsf{IF} \ B \ \mathsf{THEN} \ S_1 \ \mathsf{ELSE} \ S_2, Q) = (B \Rightarrow WLP(S_1, Q)) \land (\neg B \Rightarrow WLP(S_2, Q)) \\ & WLP(\mathsf{BEGIN} \ \mathsf{VAR} \ V_1 \dots V_n \ S \ \mathsf{END}, Q) = WLP(S, Q), \text{ where } V_1 \dots V_n \notin fv(Q) \\ & WLP(\mathsf{WHILE} \ B \ \mathsf{DO} \ \{I\} \ S, Q) = I \land ((B \land I) \Rightarrow WLP(S, I)) \land ((\neg B \land I) \Rightarrow Q) \end{split}
```



- We also make use of the distillation program transformation algorithm.
- Unfold/fold program transformation that builds on top of positive supercompilation and is strictly more powerful.
- Extra power is due to generalisation and folding being performed with respect to recursive terms.
- Terms are transformed into a normalised form called distilled form that makes it easier to identify similarities and differences between terms.
- Built-in associative operators (such as +,*,∧,∨) are always transformed into right-associative form.



- Generalisation is performed if the expression obtained from distillation is an embedding of a previously distilled one.
- The form of embedding we use is known as homeomorphic embedding.
- An expression *E* is embedded in expression E' if $E \leq E'$.

 $\frac{\exists i \in \{1 \dots n\}. E \trianglelefteq E_i}{E \trianglelefteq \phi(E_1, \dots, E_n)} \quad \frac{\forall i \in \{1 \dots n\}. E_i \trianglelefteq E'_i}{\phi(E_1, \dots, E_n) \oiint \phi(E'_1, \dots, E'_n)}$

We write E ≤ E' if expression E is coupled with expression E' using the third rule above.

▲ □ ▶ ▲ □ ▶ ▲ □ ▶



• The generalisation of expression E with respect to expression E' (denoted by $E \sqcap E'$) is defined as follows:

$$E \sqcap E' = \begin{cases} (\phi(E''_1, \dots, E''_n), \bigcup_{i=1}^n \theta_i, \bigcup_{i=1}^n \theta'_i), & \text{if } \phi = \phi' \\ \text{where} \\ E = \phi(E_1, \dots, E_n) \\ E' = \phi'(E'_1, \dots, E'_n) \\ \forall i \in \{1 \dots n\}. E_i \sqcap E'_i = (E''_i, \theta_i, \theta'_i) \\ (V, \{V \mapsto E\}, \{V \mapsto E'\}), & \text{otherwise } (V \text{ is fresh}) \end{cases}$$

• The result of this generalisation is a triple (E'', θ, θ') where E'' is the generalised expression and θ and θ' are substitutions s.t. $E''\theta \equiv E$ and $E''\theta' \equiv E'$.



- The most specific generalisation of expressions E and E' is an expression E'' such that for every other generalisation E''' of E and E', there is a substitution θ such that E''θ ≡ E'''.
- The most specific generalisation of expressions *E* and *E'* (denoted by *E*△*E'*) is computed by exhaustively applying the following rewrite rule to the triple obtained from the generalisation *E* ⊓ *E'*:

$$\begin{pmatrix} E, \\ \{V_1 \mapsto E', V_2 \mapsto E'\} \cup \theta, \\ \{V_1 \mapsto E'', V_2 \mapsto E''\} \cup \theta' \end{pmatrix} \Rightarrow \begin{pmatrix} E\{V_1 \mapsto V_2\}, \\ \{V_2 \mapsto E'\} \cup \theta, \\ \{V_2 \mapsto E''\} \cup \theta' \end{pmatrix}$$



The Induction-Iteration Method

- First proposed by Suzuki and Ishihata, 1977
- For the annotated program {P} WHILE B DO S {Q}, the logical assertion which is true if the loop is exited is calculated as follows:

$P_0 = (\neg B \Rightarrow Q)$

• Then, the weakest liberal precondition is used to calculate the logical assertion which is true before each execution of the loop body (in reverse order):

 $P_{i+1} = (B \Rightarrow WLP(S, P_i))$

• The weakest liberal precondition of the loop is given by $\bigwedge P_i$.

• Successive approximations $I_j = \bigwedge_{i=0}^{j} P_i$ are calculated until one is found that is a loop invariant.



The Induction-Iteration Method

There are a few drawbacks to this approach:

- It is not guaranteed to terminate.
 - This is avoided by limiting the number of iterations.
 - It is found that in practice very few iterations are actually required.
- There can be an exponential blow-up in clauses into increasingly larger conjunctions.
 - This is particularly the case for conditionals, which double the number of possible paths through the loop body.
 - This is also a problem for other approaches that work forwards from the precondition using a strongest postcondition semantics.
- It still requires that the programmer provides the postcondition.
 - This is much less onerous than providing loop invariants and generally forms part of the specification of the program.



To avoid exponential blow-up in clauses:

- Conjuncts of clauses are simplified using distillation.
- Resulting conjuncts are combined using generalisation.
- Conjuncts for different paths through loop body are often minor variations of each other due to effects of distillation.

To ensure termination:

- If the current approximation is an embedding of a previous one then it is generalised with respect to this previous approximation.
- This process is continued until the current approximation is a renaming of a previous one; this is then the putative invariant for the loop.
- Guaranteed to terminate since embedding relation is a well-quasi order.



Our algorithm for the automatic generation of an invariant for the loop WHILE B DO S with postcondition Q is as follows:

 $f (distill(\neg B \land Q)) \emptyset$ where

 $f \ P \ \phi = \text{if } \exists Q \in \phi \text{ s.t. } Q \equiv P \text{ (modulo variable renaming)}$ then return P else if $\exists Q \in \phi \text{ s.t. } Q \preceq P$ then $f \ P' \ \phi \text{ where } P' = P \triangle Q$ else return $f \ (\triangle_{i=1}^{n} \{ \text{distill}(B \land P_{i}) \}) \ (\phi \cup \{P\})$ where $WLP(S, P) = \bigwedge_{i=1}^{n} P_{i}$

Our Approach

The generated invariant may contain generalisation variables.

- We try to find values for these variables that satisfy each of the three requirements for loop invariants using our Poitín theorem prover (this could also be done using a SAT solver).
- For the annotated program $\{P\}$ WHILE B DO $\{I\}$ S $\{Q\}$, the initial value of variable v can be obtained by satisfying the following predicate for v_0 using the first requirement:

 $P \Rightarrow I\{v := v_0\}$

• The inductive definition of v can be obtained by satisfying the following predicate for v_{i+1} using the second requirement:

 $I\{v := v_i\} \land B \Rightarrow WLP(S, I\{v := v_{i+1}\})$

• The final value of v can be obtained by satisfying the following predicate for v_n using the third requirement:

 $(I\{v := v_n\} \land \neg B) \Rightarrow Q$



Consider again the previous example program:

```
 \{n \ge 0\} \\ x := 0; \\ y := 1; \\ WHILE x < n DO \\ BEGIN \\ x := x + 1; \\ y := y * k \\ END \\ \{y = k^n\}
```

▲ □ ▶ ▲ □ ▶ ▲ □ ▶



We calculate the logical assertion which is true if the loop is exited:

 $\neg (x < n) \land y = k^{\land} n$

This is simplified by distillation to the following:

$$\mathsf{x} \ge \mathsf{n} \land \mathsf{y} = \mathsf{k}^{\land} \mathsf{n} \tag{1}$$

Then, we calculate the logical assertion which is true before the final execution of the loop body:

$$\begin{aligned} \mathsf{WLP}(\mathsf{BEGIN}\ x := x+1; y := y * k \ \mathsf{END}, x \ge n \land y = k^{\land}n) \\ &= x+1 \ge n \land y * k = k^{\land}n \end{aligned}$$

In conjunction with the loop condition (x < n), this is simplified to the following by distillation:

$$x + 1 = n \wedge y * k = k^{\wedge}n \tag{2}$$

This is not an embedding of (1), so the calculation continues.

	Language	Loop Invariants	Distillation	Our Approach	Examples	Conclusions
Example	е					

We next calculate the logical assertion which is true before the penultimate execution of the loop body:

$$\begin{aligned} \mathsf{WLP}(\mathsf{BEGIN}\ x := x + 1; y := y * k \ \mathsf{END}, x + 1 = n \land y * k = k^{\land}n) \\ &= (x + 1) + 1 = n \land (y * k) * k = k^{\land}n \end{aligned}$$

In conjunction with the loop condition (x < n), this is simplified to the following by distillation:

$$x + 2 = n \wedge y * (k * k) = k^{\wedge}n \tag{3}$$

We can see that (3) is an embedding of (2), so (3) is generalised to produce the following:

$$x + v = n \wedge y * w = k^{\wedge}n \tag{4}$$

where v and w are new generalisation variables. This is not an embedding of (2) or (1), so the calculation continues.

	Language	Loop Invariants	Distillation	Our Approach	Examples	Conclusions
Example	e					

The logical assertion which is true before execution of the loop body is now re-calculated as follows:

 $\begin{aligned} \mathsf{WLP}(\mathsf{BEGIN}\; \mathsf{x} := \mathsf{x} + 1; \mathsf{y} := \mathsf{y} \ast \mathsf{k}\; \mathsf{END}, \mathsf{x} + \mathsf{v} = \mathsf{n} \land \mathsf{y} \ast \mathsf{w} = \mathsf{k}^{\land}\mathsf{n}) \\ &= (\mathsf{x} + 1) + \mathsf{v} = \mathsf{n} \land (\mathsf{y} \ast \mathsf{k}) \ast \mathsf{w} = \mathsf{k}^{\land}\mathsf{n} \end{aligned}$

In conjunction with the loop condition (x < n), this is simplified to the following by distillation:

$$x + (v + 1) = n \wedge y * (k * w) = k^{\wedge}n$$
(5)

We can see that (5) is an embedding of (4), so (5) is generalised to produce the following:

$$x + v' = n \wedge y * w' = k^{\wedge}n \tag{6}$$

where v' and w' are new generalisation variables. We can now see that (6) is a renaming of (4), so (6) is our putative invariant.



- We now try to find inductive definitions for the generalisation variables v' and w' from the three requirements of loop invariants using our theorem prover Poitín.
- The initial values of the generalisation variables $(v'_0 \text{ and } w'_0)$ can be determined using the first invariant requirement:

 $n \geq 0 \wedge x = 0 \wedge y = 1 \Rightarrow x + v_0' = n \wedge y \ast w_0' = k^\wedge n$

- The assignments $v'_0 := n$ and $w'_0 := k^{\wedge} n$ satisfy this assertion.
- The inductive values of the generalisation variables (v'_{i+1} and w'_{i+1}) can be determined using the second invariant requirement:

$$\begin{array}{l} x+v_i'=n \wedge y \ast w_i'=k^\wedge n \wedge x < n \Rightarrow \\ (x+1)+v_{i+1}'=n \wedge (y \ast k) \ast w_{i+1}'=k^\wedge n \end{array}$$

• The assignments $v'_{i+1} := v'_i - 1$ and $w'_{i+1} := w'_i / k$ satisfy this assertion.



 The final values of the generalisation variables (v'_n and w'_n) can be determined using the third invariant requirement:

 $x + v_n' = n \wedge y \ast w_n' = k^\wedge n \wedge \neg (x < n) \Rightarrow y = k^\wedge n$

- The assignments $v'_n := 0$ and $w'_n = 1$ satisfy this assertion.
- The discovered invariant is therefore equivalent to the following:

$$\mathsf{x} \le \mathsf{n} \land \mathsf{y} = \mathsf{k}^{\land} \mathsf{x}$$



Consider following program:

 $\{n \ge 0\}$ x := n: y := 1;z := k: WHILE x > 0 DO BEGIN IF x%2 = 1 THEN y := y * z ELSE SKIP; x := x/2;z := z * zEND $\{\mathbf{v} = \mathbf{k}^{\wedge}\mathbf{n}\}$

We use S to denote the body of the loop in the above program

• • = • • = •

э



We calculate the logical assertion which is true if the loop is exited:

 $\neg(x>0) \land y = k^{\land}n$

This is simplified by distillation to the following:

$$\mathsf{x} \le \mathsf{0} \land \mathsf{y} = \mathsf{k}^{\land}\mathsf{n} \tag{1}$$

Then, we calculate the logical assertion which is true before the final execution of the loop body:

 $WLP(S, x \le 0 \land y = k^{\land}n)$

This gives the following:

$$\begin{array}{l} (\mathsf{x}\%2=1\Rightarrow\mathsf{x}/2\leq\mathsf{0}\wedge\mathsf{y}*\mathsf{z}=\mathsf{k}^{\wedge}\mathsf{n})\\ \wedge\ (\neg(\mathsf{x}\%2=1)\Rightarrow\mathsf{x}/2\leq\mathsf{0}\wedge\mathsf{y}=\mathsf{k}^{\wedge}\mathsf{n}) \end{array}$$

In conjunction with the loop condition (x > 0), the second conjunct is simplified to True by distillation.



The first conjunct is simplified to the following:

$$x = 1 \land y * z = k^{\land} n \tag{2}$$

This is not an embedding of (1), so the calculation continues. We next calculate the logical assertion which is true before the penultimate execution of the loop body:

$$\begin{aligned} & \mathsf{WLP}(\mathsf{S},\mathsf{x}=1 \land \mathsf{y} \ast \mathsf{z}=\mathsf{k}^{\land}\mathsf{n}) \\ &= (\mathsf{x}\%2 = 1 \Rightarrow \mathsf{x}/2 = 1 \land (\mathsf{y} \ast \mathsf{z}) \ast (\mathsf{z} \ast \mathsf{z}) = \mathsf{k}^{\land}\mathsf{n}) \\ & \land (\neg(\mathsf{x}\%2 = 1) \Rightarrow \mathsf{x}/2 = 1 \land \mathsf{y} \ast (\mathsf{z} \ast \mathsf{z}) = \mathsf{k}^{\land}\mathsf{n}) \end{aligned}$$

In conjunction with the loop condition (x > 0), the first conjunct is simplified to the following by distillation:

$$x = 3 \land y \ast (z \ast (z \ast z)) = k^{\land} n$$

and the second conjunct is simplified to the following:

$$x=2 \wedge y \ast (z \ast z) = k^{\wedge} n_{\text{constant}} + \text{Constant} + \text{Constant}$$

	Language	Loop Invariants	Distillation	Our Approach	Examples	Conclusions
Example	e 2					

These are generalised with respect to each other to give:

$$x = v \wedge y * (z * w) = k^{\wedge}n$$
(3)

where v and w are new generalisation variables. This is not an embedding of (2) or (1), so the logical assertion which is true before execution of the loop body is now re-calculated as follows:

$$\begin{aligned} \mathsf{WLP}(\mathsf{S},\mathsf{x} = \mathsf{v} \land \mathsf{y} \ast (\mathsf{z} \ast \mathsf{w}) = \mathsf{k}^{\land}\mathsf{n}) \\ &= (\mathsf{x}\%2 = 1 \Rightarrow \mathsf{x}/2 = \mathsf{v} \land (\mathsf{y} \ast \mathsf{z}) \ast ((\mathsf{z} \ast \mathsf{z}) \ast \mathsf{w}) = \mathsf{k}^{\land}\mathsf{n}) \\ &\land (\neg(\mathsf{x}\%2 = 1) \Rightarrow \mathsf{x}/2 = \mathsf{v} \land \mathsf{y} \ast ((\mathsf{z} \ast \mathsf{z}) \ast \mathsf{w}) = \mathsf{k}^{\land}\mathsf{n}) \end{aligned}$$

In conjunction with the loop condition (x > 0), the first conjunct is simplified to the following by distillation:

$$x = v * 2 + 1 \land y * (z * (z * (z * w))) = k^{\land}n$$

and the second conjunct is simplified to the following:

 $x = v * 2 \land y * (z * (z * w)) = k^{\land} n_{\text{Biss}} + (z * w) = k^$



These are generalised with respect to each other to give:

$$x = v' \wedge y * (z * (z * w')) = k^{\wedge}n$$
(4)

where v' and w' are new generalisation variables. We can see that (4) is an embedding of (3), so (4) is generalised to give the following:

$$\mathbf{x} = \mathbf{v}'' \wedge \mathbf{y} * (\mathbf{z} * \mathbf{w}'') = \mathbf{k}^{\wedge} \mathbf{n}$$
(5)

where v'' and w'' are new generalisation variables. We can now see that (5) is a renaming of (3), so (5) is our putative invariant.



- We now try to find inductive definitions for the generalisation variables v" and w" from the three requirements of loop invariants using our theorem prover Poitín.
- The initial values of the generalisation variables (v_0'' and w_0'') can be determined using the first invariant requirement:

 $n \geq 0 \wedge x = n \wedge y = 1 \wedge z = k \Rightarrow x = v_0'' \wedge y * (z * w_0'') = k^{\wedge}n$

- The assignments v₀^{''} := n and w₀^{''} := k[∧](n − 1) satisfy this assertion.
- The inductive values of the generalisation variables (v^{''}_{i+1} and w^{''}_{i+1}) can be determined using the second invariant requirement:

$$\begin{array}{c} (x = v_i'' \land y \ast (z \ast w_i'') = k^{\land}n \land x > 0) \Rightarrow \\ (x\%2 = 1 \Rightarrow x/2 = v_{i+1}'' \land (y \ast z) \ast ((z \ast z) \ast w_{i+1}'') = k^{\land}n) \land \\ (\neg (x\%2 = 1) \Rightarrow x/2 = v_{i+1}'' \land y \ast ((z \ast z) \ast w_{i+1}'') = k^{\land}n) \\ \end{array}$$

- The assignments $v_{i+1}'' := v_i''/2$ and $(x\%2 = 1 \Rightarrow w_{i+1}'' := w_i''/(z * z)) \land ((\neg(x\%2 = 1) \Rightarrow w_{i+1}'' := w_i''/z)$ satisfy this assertion.
- The final values of the generalisation variables (v_n["] and w_n["]) can be determined using the third invariant requirement:

 $x=v_n''\wedge y*(z*w_n'')=k^\wedge n\wedge \neg(x>0)\Rightarrow y=k^\wedge n$

- The assignments $v_n'' := 0$ and $w_n'' = 1/z$ satisfy this assertion.
- The discovered invariant is therefore equivalent to the following:

$$x = n/2^{j} \wedge y = k^{\wedge}(n\%2^{j})$$

.



We have described a technique for automatically discovering loop invariants.

- Similar to the induction-iteration method of Suzuki and Ishihata.
- Overcomes the problem of potential non-termination.
- Avoids the potential exponential blow-up in clauses into increasingly larger conjunctions.
- Still requires that the programmer provides the postcondition for the program.
- Of course, over-generalisation can occur, and a valid loop invariant not found.



- Abstract interpretation:
 - Predicate abstraction: replace predicates with variables.
 - Constraint-based techniques over non-trivial mathematical domains (such as polynomials or convex polyhedra).
- Proof planning: Ireland and Stark, 1997
- Dynamic methods: Ernst et al., 2001
- Use of heuristics: Furia and Meyer, 2010
- Induction-iteration method: Suzuki and Ishihata, 1977



- Extending for languages with richer features.
 - Unbounded data structures such as arrays: loop invariants need to be universally quantified.
 - Pointers: separation logic extends Floyd-Hoare logic to be able to handle pointers.
- Extending to reason about termination.
 - Using the weakest precondition rather than the weakest liberal precondition.
 - Generating a variant in addition to an invariant.